



Substitute for form 1449A/PTO				<i>Complete if Known</i>	
INFORMATION DISCLOSURE STATEMENT BY APPLICANT <i>(use as many sheets as necessary)</i>				RECEIVED	
Sheet	1	of	3	Attorney Docket Number	IMMR-095/01US

PTO/SB/08A (08-00)

U.S. PATENT DOCUMENTS					
Examiner Initials*	Cite No. ¹	U.S. Patent Document		Name of Patentee or Applicant of Cited Document	Date of Publication of Cited Document MM-DD-YYYY
		Number	Kind Code ² (if known)		
RL	A1	5,785,630		Bobick, et al.	07/28/1998
	A2	5,766,016		Sinclair et al.	06/16/1998
	A3	5,547,382		Yamasaki et al.	08/20/1996
	A4	5,466,213		Hogan et al.	11/14/1995
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	A7	5,299,810		Pierce et al.	04/05/1994
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Examiner Initials*	Cite No. ¹	Foreign Patent Document		Name of Patentee or Applicant of Cited Document	Date of Publication of Cited Document MM-DD-YYYY
		Office ³	Number ⁴		
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¹ Unique citation designation number.

² See attached Kinds of U.S. Patent Documents.

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⁴ For Japanese patent documents, the indication of the year of the reign of the Emperor must precede the serial number of the patent document.

⁵ Kind of document by the appropriate symbols as indicated on the document under WIPO Standard ST. 16 if possible.

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Ronald J. Pearson



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INFORMATION DISCLOSURE STATEMENT BY APPLICANT <i>(use as many sheets as necessary)</i>				RECEIVED	
Sheet	2	of	3	Application Number	09/759,780
				Filing Date	January 12, 2001
				First Named Inventor	Erik J. SHAHOIAN
				Group Art Unit	2673
				Examiner Name	Unassigned
				Attorney Docket Number	IMMR-095/01US
				Technology Center 2600	

OTHER PRIOR ART - NON PATENT LITERATURE DOCUMENTS					
Examiner Initials*	Cite No. ¹	Include name of the author (in CAPITAL LETTERS), title of the article (when appropriate), title of the item (book, magazine, journal, serial, symposium, catalog, etc.), date, page(s), volume-issue number(s), publisher, city and/or country where published.			
	C1	Baigrie, "Electric Control Loading - A Low Cost, High Performance Alternative," <i>Proceedings of Interservice/Industry Training Systems Conference</i> , pp. 247-254, November 6-8, 1990			T ²
	C2	Iwata, "Pen-based Haptic Virtual Environment," 0-7803-1363-1/93 IEEE, pp. 287-292, 1993			
	C3	Russo, "The Design and Implementation of a Three Degree of Freedom Force Output Joystick," <i>MIT Libraries Archives</i> pp. 1-131, May 1990, archived 8/14/90			
	C4	Brooks et al., "Hand Controllers for Teleoperation - A State-of-the-Art Technology Survey and Evaluation," <i>JPL Publication 85-11</i> , NASA-CR-175890; N85-28559, pp. 1-84, 03/1/1985			
	C5	Jones et al., "A perceptual analysis of stiffness," ISSN 0014-4819 Springer International (Springer-Verlag); <i>Experimental Brain Research</i> , Vol. 79, No. 1, pp. 150-156, 1990			
	C6	Burdea et al., "Distributed Virtual Force Feedback, Lecture Notes for Workshop on Force Display in Virtual Environments and its Application to Robotic Teleoperation," <i>1993 IEEE International Conference on Robotics and Automation</i> , pp. 25-44, 05/02/1993			
	C7	Snow et al., 'Model-X Force-Reflecting-Hand-Controller,' NT Control No. NPO-17851; JPL Case No. 7348, pp. 1-4 with 45 pages of attachments, 06/15/1989			
	C8	Ouh-Young, "Force Display in Molecular Docking," Doctoral Dissertation, University of North Carolina at Chapel Hill, UMI Order No. 9034744, p. 1-369, 1990			
	C9	Tadros, "Control System Design for a Three Degree of Freedom Virtual Environment Simulator Using Motor/Brake Pair Actuators," <i>MIT Archive</i> , pp. 1-88, February 1990, archived 8/13/90			
	C10	Caldwell et al., "Enhanced Tactile Feedback (Tele-Taction) Using a Multi-Functional Sensory System," 1050-4729/93, pp. 955-960, 1993			
	C11	Adelstein et al., "Design and Implementation of a Force Reflecting Manipulandum for Manual Control research," DSC-Vol. 42, <i>Advances in Robotics</i> , pp. 1-12, 1992			
	C12	Gotow et al., "Controlled Impedance Test Apparatus for Studying Human Interpretation of Kinesthetic Feedback," WA11-11:00, pp. 332-337			
	C13	Stanley et al., "Computer Simulation of Interacting Dynamic Mechanical Systems Using Distributed Memory Parallel Processors," DSC-Vol. 42, <i>Advances in Robotics</i> , pp. 55-61, ASME 1992			
	C14	Russo, "Controlling Dissipative Magnetic Particle Brakes in Force Reflective Devices," DSC-Vol. 42, <i>Advances in Robotics</i> , pp. 63-70, ASME 1992			
	C15	Kontarinis et al., "Display of High-Frequency Tactile Information to Teleoperators," <i>Telemanipulator Technology and Space Telerobotics</i> , Won S. Kim, Editor, Proc. SPIE Vol. 2057, pp. 40-50, Sep. 7-9, 1993			
	C16	Patrick et al., "Design and Testing of A Non-reactive, Fingertip, Tactile Display for Interaction with Remote Environments," <i>Cooperative Intelligent Robotics in Space</i> , Rui J. deFigueiredo et al, Editor, Proc. SPIE Vol. 1387, pp. 215-222, 1990			
	C17	Adelstein, "A Virtual Environment System For The Study of Human Arm Tremor," <i>Ph.D. Dissertation</i> , Dept. of Mechanical Engineering, MIT, June 1989, archived 3/13/90			
	C18	Bejczy, "Sensors, Controls, and Man-Machine Interface for Advanced Teleoperation," <i>Science</i> , Vol. 208, No. 4450, pp. 1327-1335, 1980			
	C19	Bejczy et al., "Generalization of Bilateral Force-Reflecting Control of Manipulators," <i>Proceedings Of Fourth CISIM-IFToMM</i> , Sep. 8-12, 1981			
	C20	McAfee et al., "Teleoperator Subsystem/Telerobot Demonstrator: Force Reflecting Hand Controller Equipment Manual," <i>JPL 1988</i> , JPL D-5172			
	C21	Minsky, "Computational Haptics: The Sandpaper System for Synthesizing Texture for a Force-Feedback Display," <i>Ph.D. Dissertation</i> , MIT, June 1995, archived 7/6/95			
	C22	Jacobsen et al., "High Performance, Dextrous Telerobotic Manipulator With Force Reflection," <i>Intervention/ROV '91 Conference & Exposition</i> , Hollywood, Florida, May 21-23, 1991			
	C23	Shimoga, "Finger Force and Touch Feedback Issues in Dexterous Telemanipulation," <i>Proceedings of Fourth Annual Conference on Intelligent Robotic Systems for Space Exploration</i> , Rensselaer Polytechnic Institute, Sep. 30- Oct. 1, 1992			
	C24	IBM Technical Disclosure Bulletin, "Mouse Ball-Actuating Device With Force and Tactile Feedback," Vol. 32, No. 9B, February 1990			
	C25	Terry et al., "Tactile Feedback In A Computer Mouse," <i>Proceedings of Fourteenth Annual Northeast Bioengineering Conference</i> , University of New Hampshire, March 10-11, 1988			
	C26	Howe, "A Force-Reflecting Teleoperated Hand System for the Study of Tactile Sensing in Precision Manipulation," <i>Proceedings of the 1992 IEEE International Conference on Robotics and Automation</i> , Nice, France, May 1992			
	C27	Eberhardt et al., "OMAR - A Haptic display for speech perception by deaf and deaf-blind individuals," <i>IEEE Virtual Reality Annual International Symposium</i> , Seattle, WA, Sep. 18-22, 1993			
RL	C28	Rabinowitz et al., "Multidimensional tactile displays: Identification of vibratory intensity, frequency, and contractor area," <i>Journal of The Acoustical Society of America</i> , Vol. 82, No. 4, October 1987			

Ronald Aneese



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				First Named Inventor	Erik J. SHAHOIAN
				Group Art Unit	2673
				Examiner Name	Unassigned
				Attorney Docket Number	IMMR-095/01US

RL	C29	Bejczy et al., "Kinesthetic Coupling Between Operator and Remote Manipulator," <i>International Computer Technology Conference, The American Society of Mechanical Engineers</i> , San Francisco, CA, August 12-15, 1980	
	C30	Bejczy et al., "A Laboratory Breadboard System For Dual-Arm Teleoperation," <i>SOAR '89 Workshop</i> , JSC, Houston, TX, July 25-27, 1989	
	C31	Ouhyoung et al., "A Low-Cost Force Feedback Joystick and Its Use in PC Video Games," <i>IEEE Transactions on Consumer Electronics</i> , Vol. 41, No. 3, August 1995	
	C32	Marcus, "Touch Feedback in Surgery," <i>Proceedings of Virtual Reality and Medicine The Cutting Edge</i> , Sep. 8-11, 1994	
RL	C33	Bejczy, et al., "Universal Computer Control System (UCCS) For Space Telerobots," CH2413-3/87/0000/0318501.00 1987 IEEE, 1987	

*EXAMINER: Initial if reference considered, whether or not citation is in conformance with MPEP 609. Draw line through citation if not in conformance and not considered. Include copy of this form with next communication to applicant.

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